

2-52. A particle of mass m moving in one dimension has potential energy $U(x) = U_0[2(x/a)^2 - (x/a)^4]$, where U_0 and a are positive constants. (a) Find the force $F(x)$, which acts on the particle. (b) Sketch $U(x)$. Find the positions of stable and unstable equilibrium. (c) What is the angular frequency ω of oscillations about the point of stable equilibrium? (d) What is the minimum speed the particle must have at the origin to escape to infinity? (e) At $t = 0$ the particle is at the origin and its velocity is positive and equal in magnitude to the escape speed of part (d). Find $x(t)$ and sketch the result.

2-53. Which of the following forces are conservative? If conservative, find the potential energy $U(\mathbf{r})$. (a) $F_x = ayz + bx + c$, $F_y = axz + bz$, $F_z = axy + by$. (b) $F_x = -ze^{-x}$, $F_y = \ln z$, $F_z = e^{-x} + y/z$. (c) $\mathbf{F} = \mathbf{e}_r a/r$ (a, b, c are constants).

4.2** Evaluate the work done

$$W = \int_O^P \mathbf{F} \cdot d\mathbf{r} = \int_O^P (F_x dx + F_y dy) \quad (4.100)$$

by the two-dimensional force $\mathbf{F} = (x^2, 2xy)$ along the three paths joining the origin to the point $P = (1, 1)$ as shown in Figure 4.24(a) and defined as follows: (a) This path goes along the x axis to $Q = (1, 0)$ and then straight up to P . (Divide the integral into two pieces, $\int_O^P = \int_O^Q + \int_Q^P$.) (b) On this path $y = x^2$, and you can replace the term dy in (4.100) by $dy = 2x dx$ and convert the whole integral into an integral over x . (c) This path is given parametrically as $x = t^3$, $y = t^2$. In this case rewrite x, y, dx , and dy in (4.100) in terms of t and dt , and convert the integral into an integral over t .

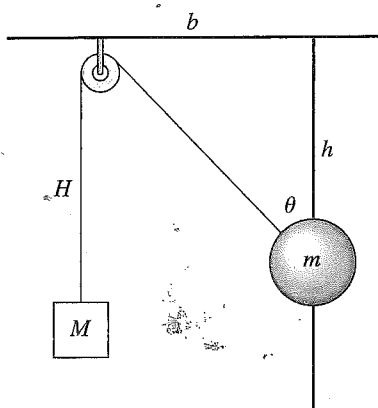


Figure 4.27 Problem 4.36

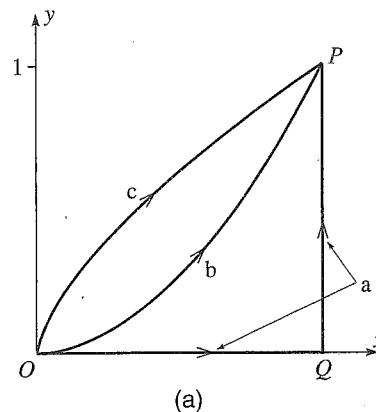


Figure 4.24

4.12* Calculate the gradient ∇f of the following functions, $f(x, y, z)$: (a) $f = x^2 + z^3$. (b) $f = ky$, where k is a constant. (c) $f = r \equiv \sqrt{x^2 + y^2 + z^2}$. [Hint: Use the chain rule.] (d) $f = 1/r$.

4.36** A metal ball (mass m) with a hole through it is threaded on a frictionless vertical rod. A massless string (length l) attached to the ball runs over a massless, frictionless pulley and supports a block of mass M , as shown in Figure 4.27. The positions of the two masses can be specified by the one angle θ . (a) Write down the potential energy $U(\theta)$. (The PE is given easily in terms of the heights shown as h and H . Eliminate these two variables in favor of θ and the constants b and l . Assume that the pulley and ball have negligible size.) (b) By differentiating $U(\theta)$ find whether the system has an equilibrium position, and for what values of m and M equilibrium can occur. Discuss the stability of any equilibrium positions.